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# 2 Rayleigh Disk

Richard Rippel

# 2 Rayleigh Disk

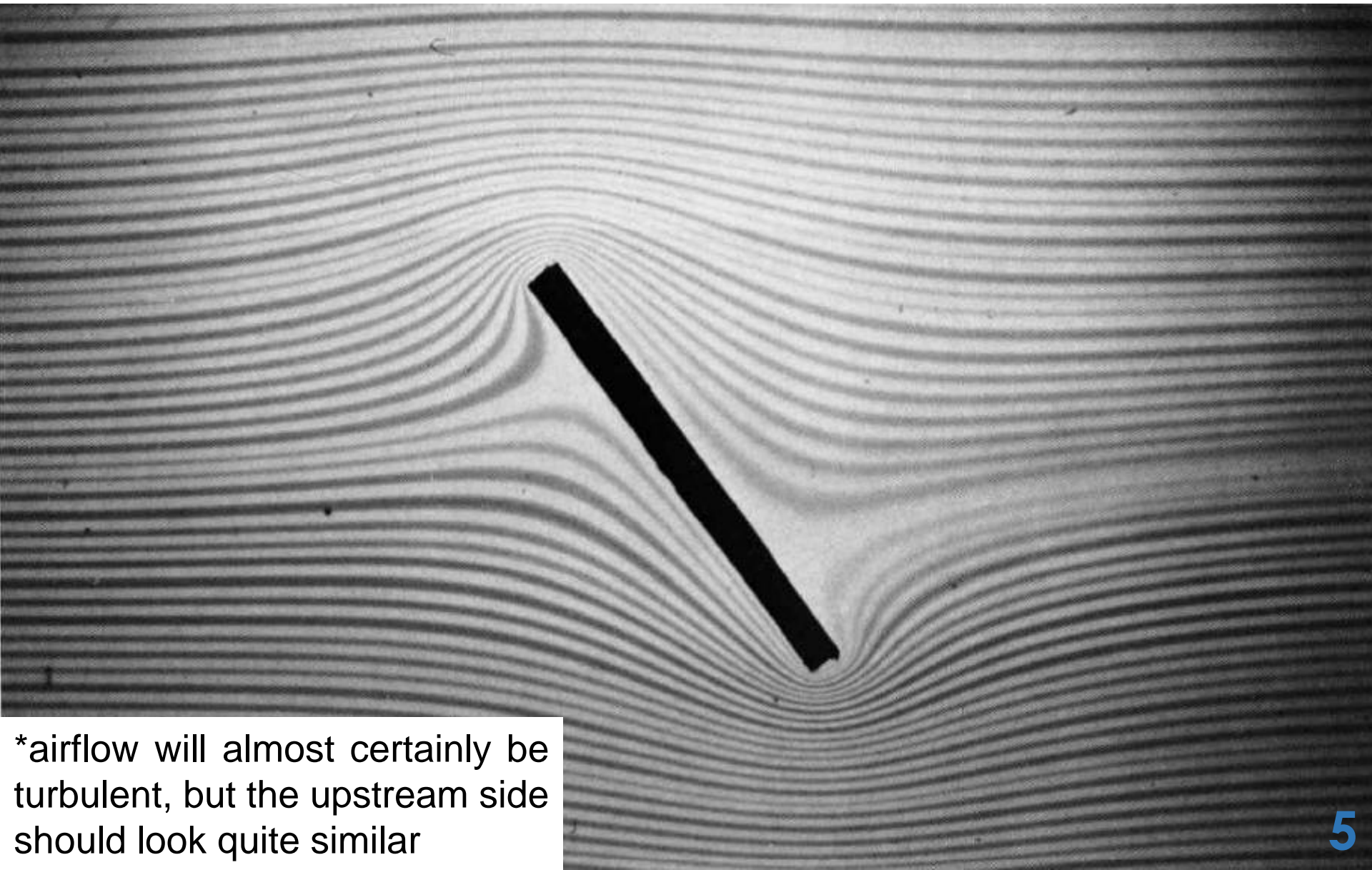
A disk suspended vertically by a thin thread is placed in an acoustic field. This device can be used to measure the intensity of sound by turning about the axis of the thread. Investigate the accuracy of such a device.

Disk zvislo zavesený na tenkej nitke vložte do akustického poľa. Takéto zariadenie je možné použiť na meranie intenzity zvuku pomocou otočenia disku okolo nitky. Preskúmajte presnosť takéhoto zariadenia.



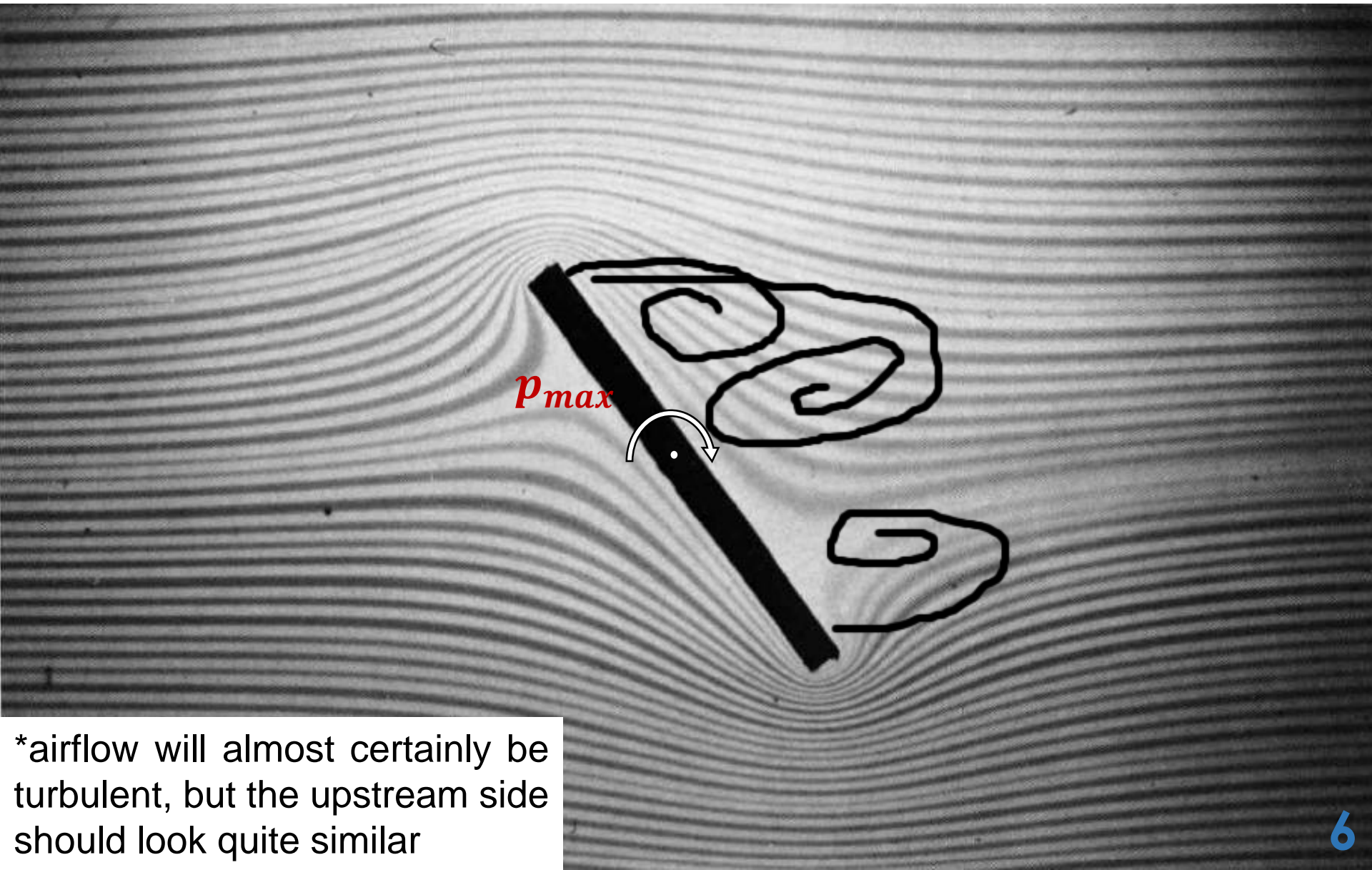
# Basic explanation

# Flow around an inclined plate



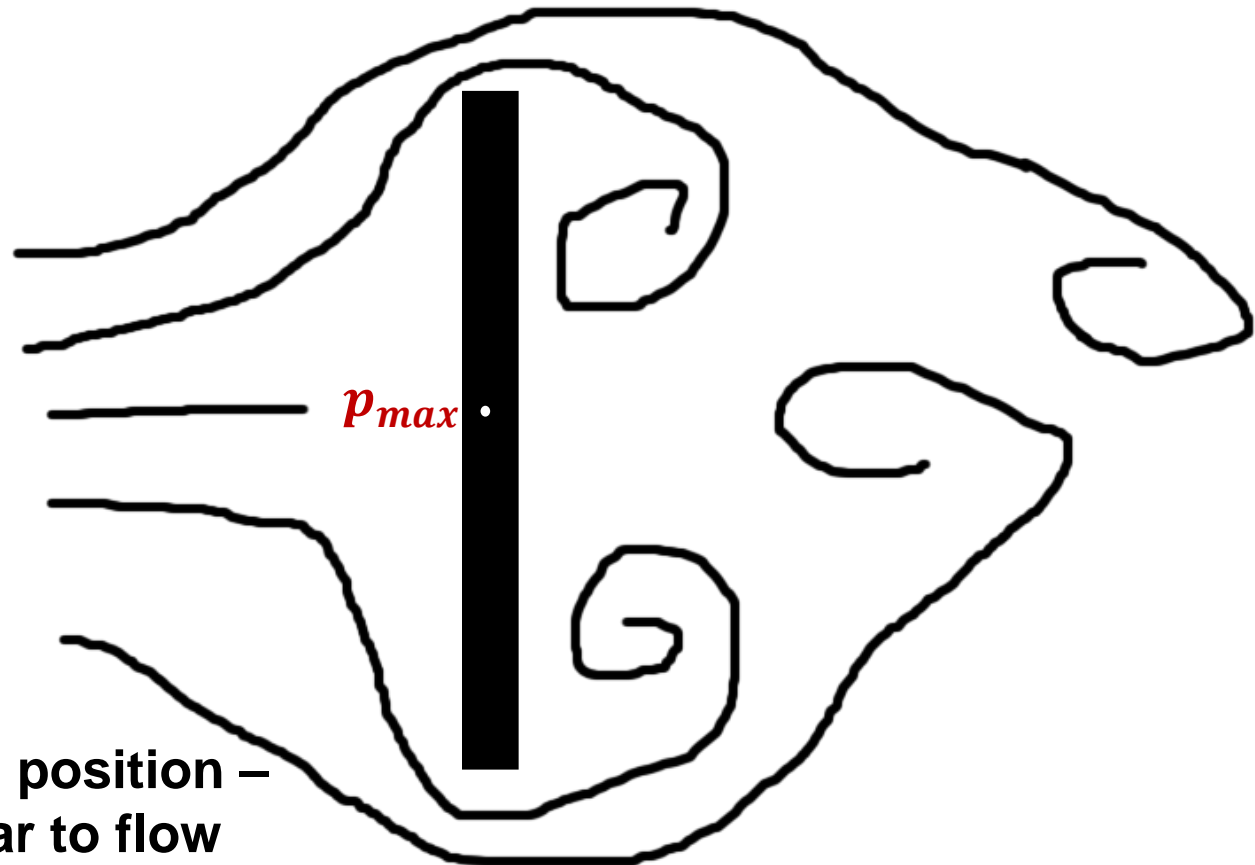
\*airflow will almost certainly be turbulent, but the upstream side should look quite similar

# Flow around an inclined plate



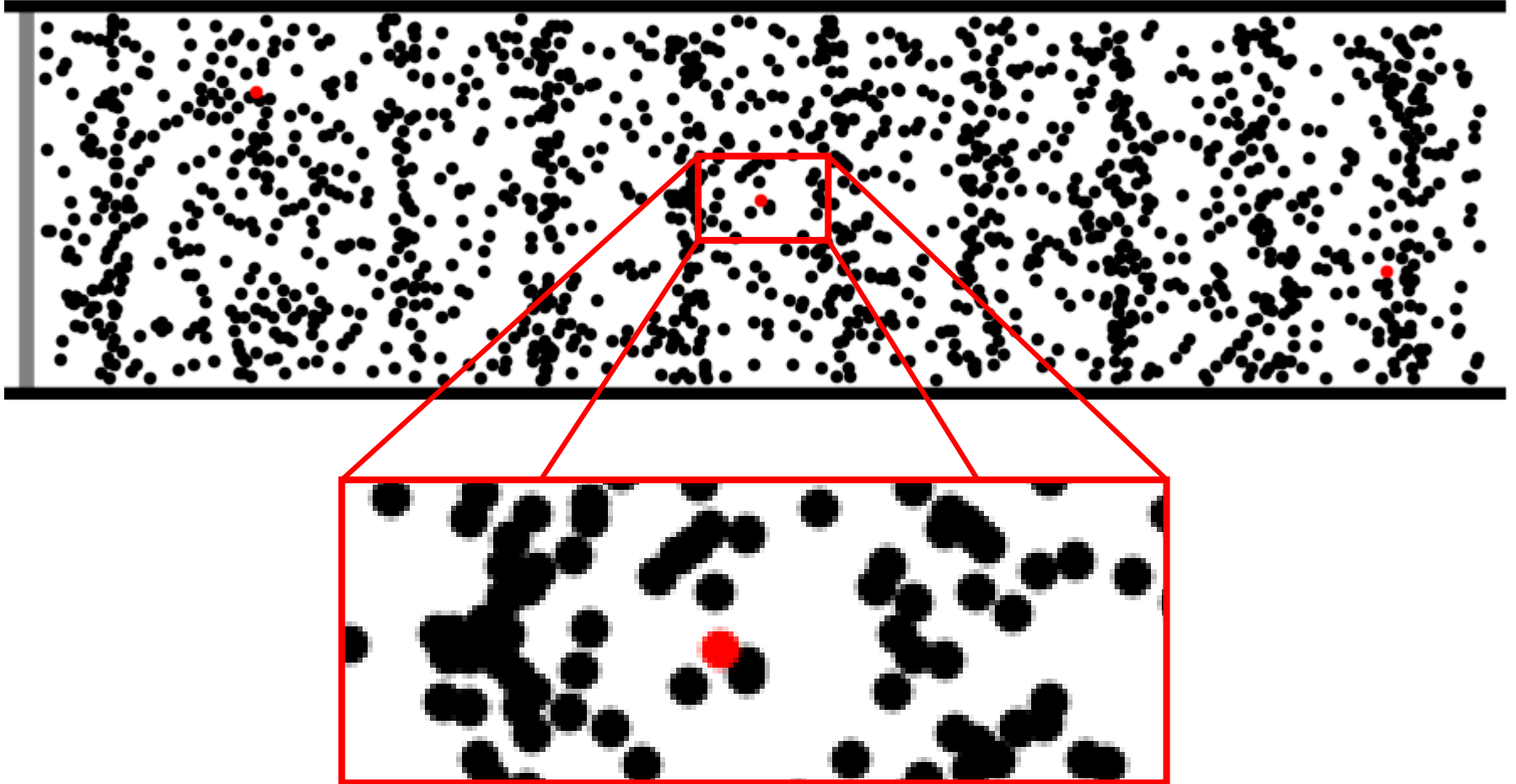
\*airflow will almost certainly be turbulent, but the upstream side should look quite similar

# Flow around a plate



**stable equilibrium position –  
disk perpendicular to flow**  
note that the same would apply for  
flow in the opposite direction

# Sound wave



Flow with alternating direction

equilibrium position of disk perpendicular to wave propagation



# Effect of thread

Torque acting to the initial position (due to torsional stiffness of the thread)

-> equilibrium position shifted by some angle

**Some theory**

# Sound intensity

- power carried by sound waves per unit area [W/m<sup>2</sup>]
- defined as

$$I = p v$$

- time averaged sound intensity

$$\langle I \rangle = \frac{1}{T} \int_0^T p(t) v(t) dt = \rho c \langle v^2 \rangle$$

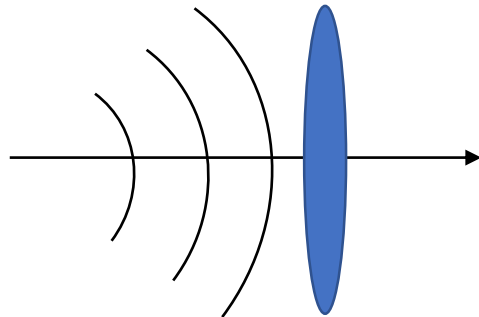
$p$  – acoustic pressure (local pressure deviation from the ambient)

$v$  – particle velocity (speed of a small part of fluid as it moves back and forth in the sound wave)

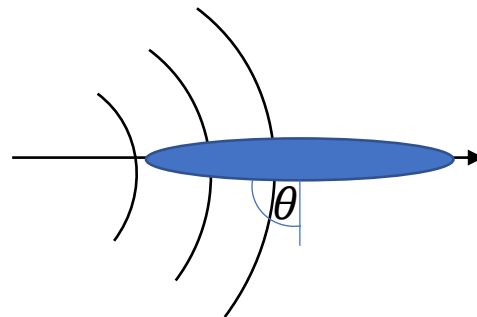
$c$  – speed of sound

$\rho$  – air density

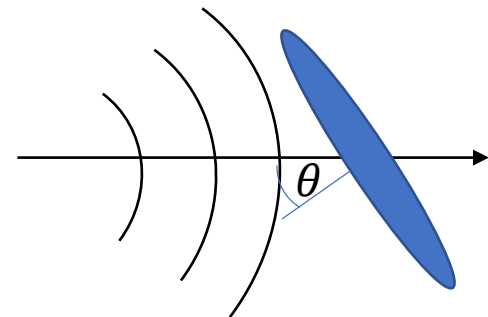
# Sound induced torque



no torque



no torque



torque

$$\tau \sim \sin 2\theta$$

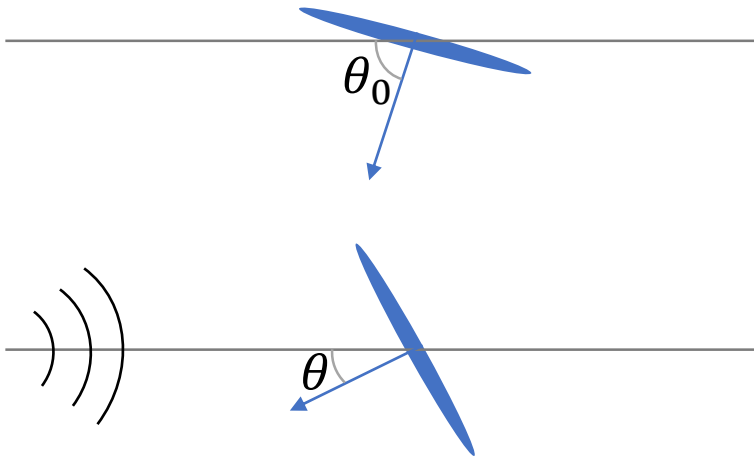
other parameters: fluid density, fluid velocity, disk size

$$\tau \sim \rho^a v^b r^c \quad kg \cdot m^2 \cdot s^{-2} = (kg \cdot m^{-3})^a \cdot (m \cdot s^{-1})^b \cdot m^c$$

$$\tau \sim \rho v^2 r^3$$

$$\tau = \frac{4}{3} \rho r^3 \langle v^2 \rangle \sin 2\theta$$

# Torque from the thread



$$\tau = -k\Delta\theta = -k(\theta - \theta_0)$$

$k$  – torsional stiffness of the thread

# Intensity vs angle

Intensity & velocity relation:

$$\langle I \rangle = \rho c \langle v^2 \rangle$$

Flow induced torque:

$$\tau = \frac{4}{3} \rho r^3 \langle v^2 \rangle \sin 2\theta \quad \Rightarrow \quad \langle I \rangle = \frac{3ck(\theta_0 - \theta)}{4\rho r^3 \sin 2\theta}$$

Torque from the thread:

$$\tau = -k(\theta - \theta_0)$$

Doesn't take into account:

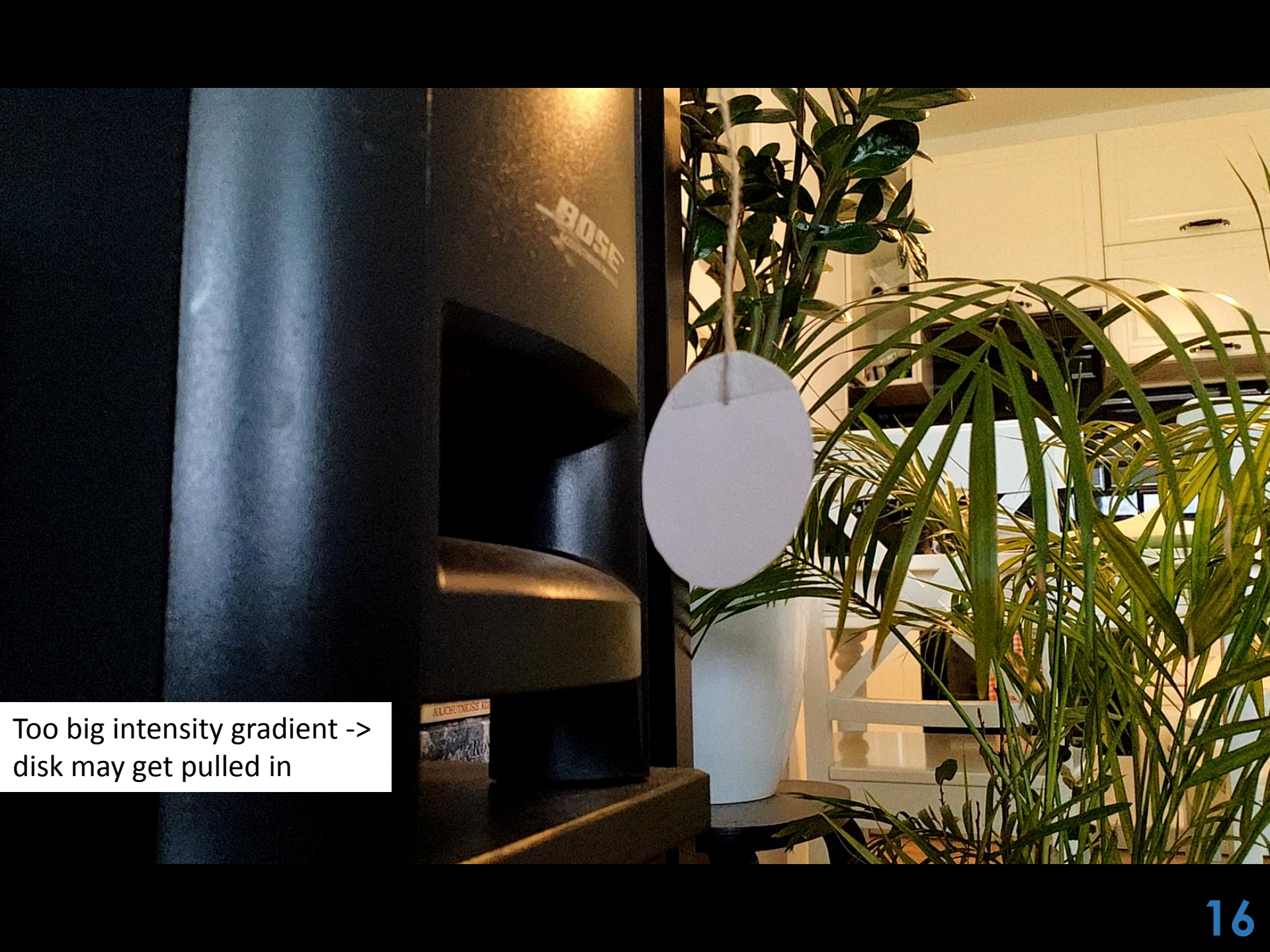
- diffraction of the sound by the disk
- finite inertia of the disk
- finite thickness of the disk

Articles providing corrections – e.g. reference [2]

Will it hold for wavelengths smaller than the disk diameter?

Think it through, try it

# Tips for experiments



Too big intensity gradient ->  
disk may get pulled in



# Angle measurement

The screenshot shows the Tracker software interface. The main window displays a video of a string being measured. A green dot is placed on the string, and two magenta lines are drawn from it to the axes, forming a right-angled triangle. The angle between the string and the horizontal axis is labeled as 35.0°. The video window also shows the coordinates of the dot:  $x = -98,33$  and  $y = 246,7$ .

The graph window shows the angle  $\theta$  in degrees versus time  $t$  in seconds. The angle is constant at 35.01 degrees over the 7-second interval.

The data table below the graph shows the following data:

t (s)	$\theta$
0,000	35,0°
0,067	35,0°
0,100	35,0°
0,133	35,0°
0,167	35,0°
0,200	35,0°
0,233	35,0°
0,267	35,0°
0,300	35,0°
0,333	35,0°

- Put camera close to the axis of the thread
- Arrange it so that you know direction of sound propagation

# Sound intensity measurement

option 1

Your school might have one of these



Can measure sound intensity level  $L$  [dB]

$$L = 10 \log_{10} \left( \frac{I}{I_0} \right)$$

$$I = I_0 10^{L/10}$$

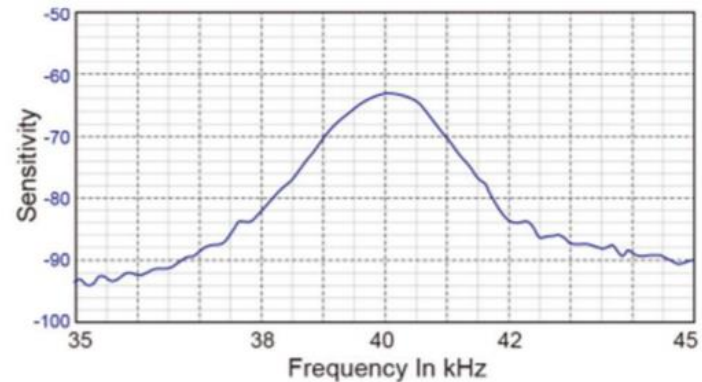
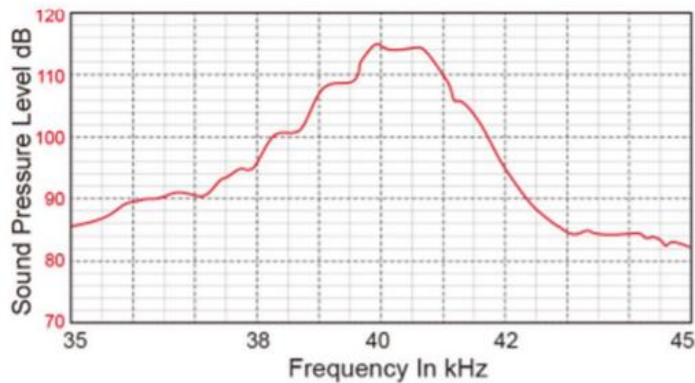
where

$$I_0 = 10^{-12} \text{W/m}^2$$

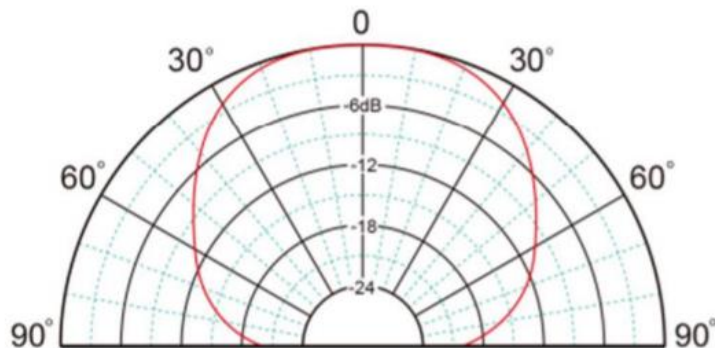
# Sound intensity measurement

option 2

### Sound Pressure Level & Sensitivity



### Directivity



Some speakers and ultrasound transducer come with detailed datasheets

Efficiency/sensitivity graph – how much of the input power gets converted to sound at each frequency

Directivity graph – how is the output power distributed in space

# Sound intensity measurement

## option 3

### Relative intensity

Can't get a good intensity measurement -> use multiples of a reference intensity in graphs

$I \sim P$  (P-speaker input power) within reasonable power range

$I \sim \frac{1}{R^2}$  (R-distance from speaker) ! only for spherical wave – won't be accurate for most speakers

# Torsional stiffness of the thread

Torsional pendulum

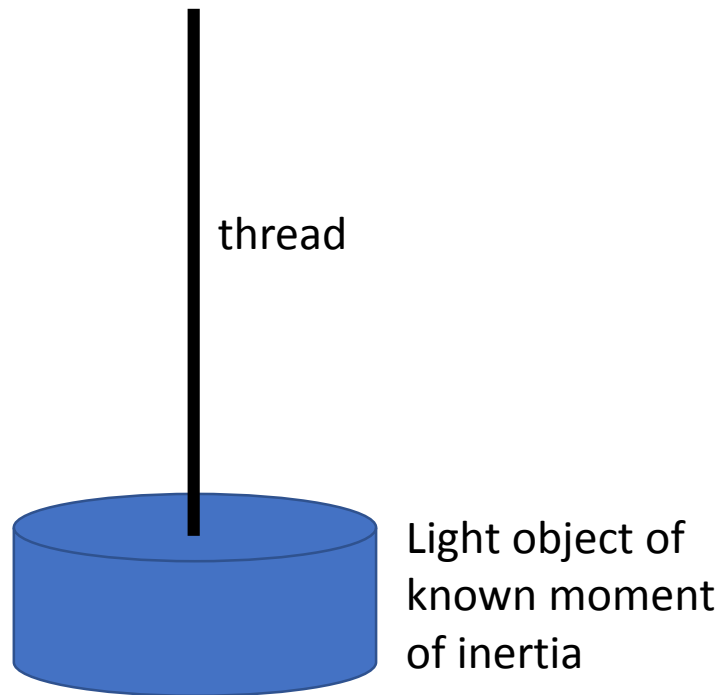
$$T = 2\pi \sqrt{\frac{J}{k}}$$

$T$  – period of oscillations

$k$  – torsional stiffness

$J$  – moment of inertia

for cylinder:  $J = \frac{1}{2}mr^2$



Make sure that:

- Object is centered and its axis of symmetry is coincident with the thread
- Oscillations don't die out too quickly
- Object isn't putting too much tension to the thread

**To do**

# To do

## Minimum

- Give a basic explanation
- Build a setup
- Measure angle vs intensity (at least relative) for a few  $\theta_0$
- Draw some qualitative conclusions about accuracy/precision and how they depend on  $\theta_0$  and  $I$

## Some more

- Try changing other parameters
- Make quantitative comparison between measured and theoretical  $I$  vs  $\theta$
- Quantify the accuracy/precision
- If I give you a sound can you give me  $I = \text{value} \pm \text{uncertainty}$  ?

## If the else is done

- Try wavelengths smaller than disk, is the behaviour frequency dependent?
- Read articles and apply necessary corrections to the theory, if there are still discrepancies analyse them

**THANK YOU**